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this book explores the complex interplay between maritime insurance and piracy in the indian ocean a crucial global trade route drawing on rich oral histories this work delves into the lives of seafarers and insurance experts who confront the harsh realities of somali piracy through a series of compelling case studies including the notorious maersk alabama hijacking the book sheds light on the evolving role of maritime insurers as they navigate the precarious waters of risk management it highlights how these companies not only provide financial protection but also shape maritime security practices transforming the sea into a managed space of governance spanning a geographical range from the horn of africa to global maritime hubs the book emphasises the human cost of piracy and the often overlooked experiences of those at sea bridging between historical cases and contemporary challenges the book advocates a deeper understanding of the maritime landscape furthermore by exploring the perspectives of seafarers the book provides a unique insight into the emerging challenges faced at sea and the importance of safety in moments of maritime insecurity this book will be of much interest to students of maritime security naval policy the history of insurance and international relations

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this edited volume adopts a global perspective to review how dogs interact with wildlife how humans perceive these interactions the potential importance of dog wildlife interactions and the scope of the problems

screw theory is an effective and efficient method used in robotics applications this book demonstrates how to implement screw theory explaining the key fundamentals and real world applications using a practical and visual approach an essential tool for those involved in the development of robotics implementations the book uses case studies to analyze mechatronics screw theory offers a significant opportunity to interpret mechanics at a high level facilitating contemporary geometric techniques in solving common robotics issues using these solutions results in an optimized performance in comparison to algebraic and numerical options demonstrating techniques such as six dimensional 6d vector notation and the product of exponentials poe the use of screw theory notation reduces the need for complex algebra which results in simpler code which is easier to write comprehend and debug the book provides exercises and simulations to demonstrate this with new formulas and algorithms presented to aid the reader in accelerating their learning by walking the user through the fundamentals of screw theory and by providing a complete set of examples for the most common robot manipulator architecture the book delivers an excellent foundation through which to comprehend screw theory developments the visual approach of the book means it can be used as a self learning tool for professionals alongside students it will be of interest to those studying robotics mechanics mechanical engineering and electrical engineering

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