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since the appearance of vol 1 of models of neural networks in 1991
the theory of neural nets has focused on two paradigms information

coding through coherent firing of the neurons and functional feedback information coding through coherent neuronal firing exploits time as a cardinal degree of freedom this capacity of a neural network rests on the fact that the neuronal action potential is a short say 1 ms spike localized in space and time spatial as well as temporal correlations of activity may represent different states of a network in particular temporal correlations of activity may express that neurons process the same object of for example a visual scene by spiking at the very same time the traditional description of a neural network through a firing rate the famous s shaped curve presupposes a wide time window of say at least 100 ms it thus fails to exploit the capacity to bind sets of coherently firing neurons for the purpose of both scene segmentation and figure ground segregation feedback is a dominant feature of the structural organization of the brain recurrent neural networks have been studied extensively in the physical literature starting with the ground breaking work of john hopfield 1982

this open access textbook provides an in depth introduction into the crispr cas9 technology and explores its use across the gamut of biological model systems as the subject has risen from a significant new discovery to a mainstream molecular biology practice it is essential that students of molecular biology understand the fundamentals behind crispr cas9 technology and how it may be employed efficiently and ethically in research this volume edited by experts in both molecular biology and undergraduate education will teach not only the fundamentals of using crispr cas9 but also how to successfully employ this technology in classroom settings the book is written for undergraduates and advanced high school classes in the area of molecular biology genetics genomics and biological engineering and will provide a perfect tool for undergraduate lecturers to prepare their classes

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consider the problem of a robot algorithm learning mechanism moving along the real line attempting to locate a particular point to assist the mechanism we assume that it can communicate with an environment oracle which guides it with information regarding the direction in which it should go if the environment is deterministic the problem is the deterministic point location problem which has been studied rather thoroughly 1 in its pioneering version 1 the problem was presented in the setting that

the environment could charge the robot a cost which was proportional to the distance it was from the point sought for the question of having multiple communicating robots locate a point on the line has also been studied 1 2 in the stochastic version of this problem we consider the scenario when the learning mechanism attempts to locate a point in an interval with stochastic i e possibly erroneous instead of deterministic responses from the environment thus when it should really be moving to the right it may be advised to move to the left and vice versa apart from the problem being of importance in its own right the stochastic pointlocationproblemalsohas potentialapplications insolvingoptimization problems inmanyoptimizationsolutions forexampleinimageprocessing p tern recognition and neural computing 5 9 11 12 14 16 19 the algorithm worksits wayfromits currentsolutionto the optimal solutionbasedoninformation that it currentlyhas a crucialquestionis oneof determining the parameter whichtheoptimizationalgorithmshoulduse

the avec symposium is a leading international conference in the fields of vehicle dynamics and advanced vehicle control bringing together scientists and engineers from academia and automotive industry the first symposium was held in 1992 in yokohama japan since then biennial avec symposia have been established internationally and have considerably contributed to the progress of technology in automotive research and development in 2016 the 13th international symposium on advanced vehicle control avec 16 was held in munich germany from 13th to 16th of september 2016 the symposium was hosted by the munich university of applied sciences avec 16 puts a special focus on automatic driving autonomous driving functions and driver assist systems integrated control of interacting control systems controlled suspension systems active wheel torque distribution and vehicle state and parameter estimation 132 papers were presented at the symposium and are published in these proceedings as full paper contributions the papers review the latest research developments and practical applications in highly relevant areas of vehicle control and may serve as a reference for researchers and engineers

this book aims to popularize physics by emphasizing conceptual ideas of physics and their interconnections while avoiding mathematics entirely the approach is to explore intriguing topics by asking and discussing questions thereby the reader can participate in developing answers which enables a deeper understanding than is achievable with memorization the topic of this volume colors light and optical illusions is chosen because we face colors and light every waking minute of our lives and we experience optical illusions much more often than we realize this book will attract all those with a curious mind about nature and with a desire to understand how nature works especially the

younger generation of secondary school children and their teachers

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